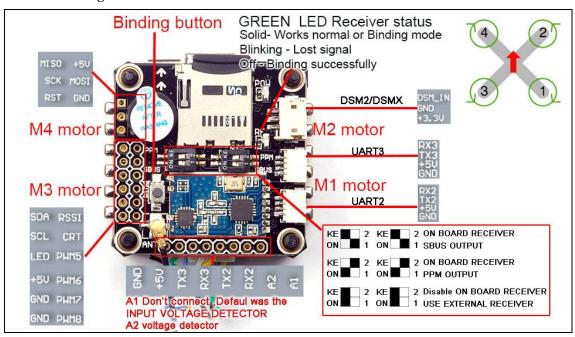
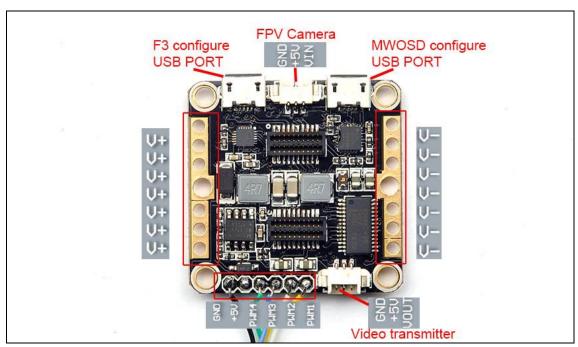
RacerCuber Manual

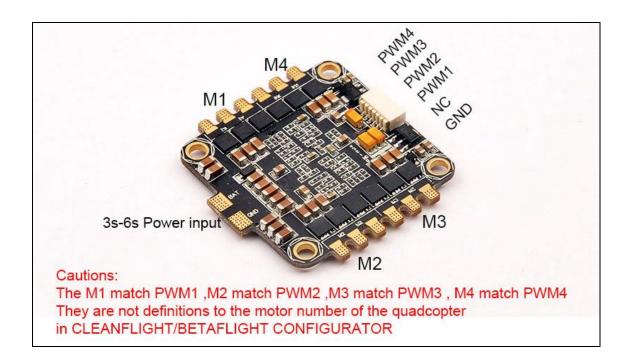
Connection Diagram





Racercube FEATURES

F3_EVO FLIGHT CONTROLLER Jaw-Dropping Flight Performance
CLEANFLIGHT/BETAFLIGHT support
4IN1 ESC Little BEE 20A F396 Chip ESC Ready, BLHELI Pass-through Ready
FRSKY Compatible RX-F802 D8 MODE SBUS/PPM RECEIVER Ready
MWOSD Ready
RSSI/ VOLTAGE DETECOTR Ready
BUZZER READY



SPECFICTAION:

1.Racercube Flight controller

Firmware: Cleanflight 1.13.0 Target: SP RACING F3 EVO

STM32F303 CPU, 72Mhz inc FPU

MPU9250 accelerometer/gyro/compass (connected via SPI)

BMP280 barometer

Compatible PPM/CPPM/SBUS/DSM2/DSMX Receiver

Built-in MW OSD

Integrate PDB support 2s-6s Input

2.Racercube Receiver module

Channel: 8

Working voltage: 4-6.5V

Frequency range: 2400-2483.5Mhz

Output signal: SBUS/PPM

Dual way transmission: Yes(D8 mode)

Transmit distance: > 1Km

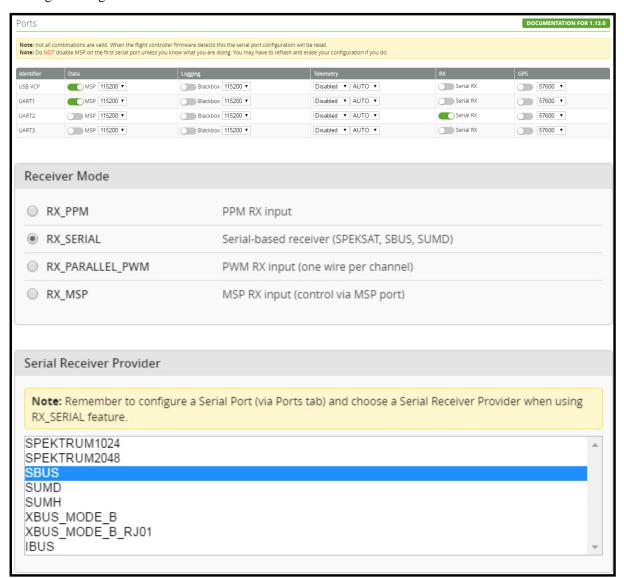
Feedback signal: RSSI, 3S voltage (A1)

With Failsafe @Throttle 3ch

Compatible with X9D(D8 mode)/XJT (D8 mode)/DJI/DFT/DHT

Receiver configuration in Cleanflight:

Enable Seria_RX for UART2 and Set Receiver mode RX_SERIAL ,Select SBUS in Cleanflight or Betaflight Configurator.



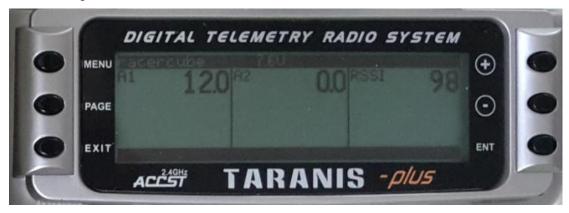
Binding procedure:

Power for the Racercube while holding the binding button, the green LED will getting to be solid, this indicate the receiver is in binding mode

Turn on the transmitter and set the receiver mode to D8 mode, then move to ENT, press it and the transmitter beeps. The green LED will turn off once the binding procedure successfully.

RSSI and Telemetry

A1/A2 Voltage detector, RSSI



After binding successful, turn on the transmitter ,move to the option TELEMETRY, then click "Discover new sensors"



Set Screen to show the Telemetry info



2.Racercube 4in1 ESC module

F396 MCU, 48Mhz Runs BLHELI LittieBee Pro 20A firmware

Support 3-6S Li-po

4PWM input,

Supports oneshot PWM

Only 35x35mm, mount holes 30x30mm (on new batch, the holes will bechanged to 30.5x30.5mm)

Supports damped light

no BEC output